

Localized coherence in two interacting populations of social agents

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We investigate the emergence of localized coherent behavior in a system consisting of two populations of social agents possessing a condition for non-interacting states, mutually coupled through global interaction fields. As an example of such dynamics, we employ Axelrod's model for social influence. The global interaction fields correspond to the statistical mode of the states of the agents in each population. We find localized coherent states for some values of parameters, consisting of one population in a homogeneous state and the other in a disordered state. This situation can be considered as a social analogue to a chimera state arising in two interacting populations of oscillators. In addition, other asymptotic collective behaviors appear depending on parameter values: a common homogeneous state, where both populations reach the same state; different homogeneous states, where both population reach homogeneous states different from each other; and a disordered state, where both populations reach inhomogeneous states.

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The study of the collective behaviors in systems consisting of two interacting populations of dynamical elements is a topic of much interest in various sciences. These systems are characterized by the presence of non-local interactions between elements in different populations. Examples of such systems arise in the coexistence of biological species [1–3], the competition of two languages in space [4], and in the dynamics of two networks of coupled oscillators [5–7].

Recently, a remarkable phenomena called chimera [8, 9] has been found in systems consisting of two populations of oscillators subject to reciprocal interactions [7, 10, 11]. In a chimera state, one population exhibits a coherent or synchronized behavior while the other is incoherent or desynchronized. The recent experimental discovery of such chimera states has fundamental implications as it shows that localized coherence and structured patterns can emerge from otherwise structureless systems [12, 13]. As noted in Ref. [7], analogous symmetry breaking is observed in dolphins and other animals that have evolved to sleep with only half of their brain at a time: neurons exhibit synchronized activity in the sleeping hemisphere and desynchronized activity in the hemisphere that is awake [14].

In this paper we investigate the emergence of localized coherence in a system consisting of two populations of social agents coupled through reciprocal global interactions. As interaction dynamics, we employ Axelrod's [15] rules for the dissemination of culture among agents in a society, a model that has attracted much attention from physicists [16–24]. In this model, the agent-agent interaction rule is such that no interaction exists for some relative values characterizing the states of the agents that compose the system. This type of interaction is common in social and biological systems where there is often some bound for the occurrence of interaction between agents, such as a similarity condition for the state vari-

able [25–29]. The global interactions act as fields [19] that can be interpreted as mass media messages originated in each population. Thus, our system can serve as a model for cross-cultural interactions between two social groups, each with its own internal dynamics, but getting information about each other through their reciprocal mass media influences [30]. In particular, the study of cross-cultural experiences through mass-mediated contacts is a relevant issue in the Social Sciences [31–33].

We show that, under some circumstances, one population reaches a homogeneous state while a disordered state appears on the other. This configuration is similar to a chimera state arising in two populations of oscillators subject to global interactions.

We consider a system of N agents divided into two populations: α and β , with sizes N_α and N_β , such that $N = N_\alpha + N_\beta$. Each population consists of a fully connected network, i. e., every agent can interact with any other within a population. We use the notation $[z]$ to indicate “or z ”. The state of agent $i \in \alpha[\beta]$ is given by an F -component vector $x_{\alpha[\beta]}^f(i)$, ($f = 1, 2, \dots, F$), where each component can take any of q different values $x_{\alpha[\beta]}^f(i) \in \{0, 1, \dots, q-1\}$. Here we define the normalized parameter $Q \equiv 1 - (1 - 1/q)^F$ to express the decreasing number of initial options per component, such that $Q = 0$ for $q \rightarrow \infty$ (many options), and $Q = 1$ for $q = 1$ (one option).

We denote by $M_\alpha = (M_\alpha^1, \dots, M_\alpha^f, \dots, M_\alpha^F)$ and $M_\beta = (M_\beta^1, \dots, M_\beta^f, \dots, M_\beta^F)$ the global fields defined as the statistical modes of the states in the populations α and β , respectively, at a given time. Thus, the component $M_{\alpha[\beta]}^f$ is assigned the most abundant value exhibited by the f th component of all the state vectors $x_{\alpha[\beta]}^f(i)$ in the population $\alpha[\beta]$. If the maximally abundant value is not unique, one of the possibilities is chosen at random with equal probability. In the context of social dynamics,

these global fields correspond to cultural “trends” associated to each population. Each agent in population α is subject to the influence of the global field M_β , and each agent in population β is subject to the influence of the global field M_α . Then, the global fields can be interpreted as reciprocal mass media messages originated in one population and being transmitted to the other.

The states $x_{\alpha[\beta]}^f(i)$ are initially assigned at random with a uniform distribution in each population. At any given time, a randomly selected agent in population $\alpha[\beta]$ can interact either with the global field $M_{\beta[\alpha]}$ or with any other agent belonging to $\alpha[\beta]$, in each case according to the dynamics of Axelrod’s cultural model. The dynamics of the system is defined by the following iterative algorithm:

1. Select at random an agent $i \in \alpha$ and a agent $j \in \beta$.
2. Select the source of interaction: with probability B , agent $i \in \alpha$ interacts with field M_β and agent $j \in \beta$ interacts with field M_α , while with probability $1 - B$, i interacts with $k \in \alpha$ selected at random and j interacts with $l \in \beta$ also selected at random.
3. Calculate the overlap, i. e., the number of shared components, between the state of agent $i \in \alpha$ and the state of its source of interaction, defined by $d_\alpha(i, y) = \sum_{f=1}^F \delta_{x_\alpha^f(i), y^f}$, where $y^f = M_\beta^f$ if the source is the field M_β , or $y^f = x_\alpha^f(k)$ if the source is agent $k \in \alpha$. Similarly, calculate the overlap $d_\beta(j, y) = \sum_{f=1}^F \delta_{x_\beta^f(j), y^f}$, where $y^f = M_\alpha^f$ if the source is the field M_α , or $y^f = x_\beta^f(l)$ if the source is agent $l \in \beta$. Here we employ the delta Kronecker function, $\delta_{x,y} = 1$, if $x = y$; $\delta_{x,y} = 0$, if $x \neq y$.
4. If $0 < d_\alpha(i, y) < F$, with probability $\frac{d_\alpha(i,y)}{F}$ choose g such that $x_\alpha^g(i) \neq y^g$ and set $x_\alpha^g(i) = y^g$; if $d_\alpha(i, y) = 0$ or $d_\alpha(i, y) = F$, the state $x_\alpha^f(i)$ does not change. If $0 < d_\beta(j, y) < F$, with probability $\frac{d_\beta(j,y)}{F}$ choose h such that $x_\beta^h(j) \neq y^h$ and set $x_\beta^h(j) = y^h$; if $d_\beta(j, y) = 0$ or $d_\beta(j, y) = F$, the state $x_\beta^f(j)$ does not change.
5. If the source of interaction is $M_{\beta[\alpha]}$, update the fields M_α and M_β .

In step 2, the parameter $B \in [0, 1]$ describes the probability for the agent-field interactions and represents the strength of the fields M_α and M_β . Steps 3 and 4 describe the interaction rules from Axelrod’s model for social influence. Step 5 characterizes the time scale for the updating of the global fields. The non-instantaneous updating of the global fields expresses the delay with which a population acquires knowledge about the other through the only available communication channel between them, as described in many societies experiencing cross-cultural interactions through mass media [31].

In the asymptotic state, both populations α and β form domains of different sizes. A domain is a set of connected agents that share the same state. A homogeneous state in population $\alpha[\beta]$ is characterized by $d_\alpha(i, j) = F$, $\forall i, j \in \alpha[\beta]$. There are q^F equivalent configurations for this state. The coexistence of several domains in a population corresponds to an inhomogeneous or disordered state.

For $B = 0$, we have two uncoupled and independent populations. It is known [16, 17] that a single system subject to Axelrod’s dynamics asymptotically reaches a homogeneous phase for values $q < q_c$, and a disordered phase for $q > q_c$, where q_c is a critical point. For fully connected networks, the value q_c depends on the system size [34]. In terms of the parameter Q , the disordered phase occurs for $Q < Q_c = 1 - (1 - 1/q_c)^F$ and the homogeneous phase takes place for $Q > Q_c$.

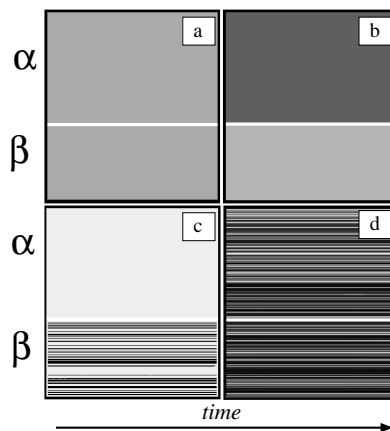


FIG. 1: Asymptotic states (vertical axis) of the agents in interacting populations α (upper part) and β (lower part) vs. time (horizontal axis) represented in grey colors, for different values of parameters, with fixed $F = 10$. Each vector state variable of an agent is represented by a different shade of grey. Population sizes are $N_\alpha = 0.6N$, $N_\beta = 0.6N$, with $N = 800$. (a) $B = 0.001$, $Q = 0.118$ (common homogeneous state). (b) $B = 0.001$, $Q = 0.095$ (different homogeneous states). (c) $B = 0.05$, $Q = 0.12$ (localized coherent state). (d) $B = 0.25$, $Q = 0.004$ (disordered state).

As the intensity of the global fields B is increased, the system exhibits diverse asymptotic behaviors for different values of the parameter Q . Figure 1 displays the asymptotic spatiotemporal patterns corresponding to the main behaviors observed: (a) a common homogeneous state, where both populations reach the same state, $M_\alpha = M_\beta$; (b) different homogeneous states, where both populations reach homogenous states different from each other, $M_\alpha \neq M_\beta$; (c) localized coherent state, where a homogeneous state occurs in only one population while the other is inhomogeneous; and (d) a disordered state, where both populations reach inhomogeneous states for values $Q < Q_c$.

The collective behaviors of the system can be charac-

terized by employing the following statistical quantities: (i) the average normalized size (divided by $N_{\alpha[\beta]}$) of the largest domain in $\alpha[\beta]$, denoted by $S_{\alpha[\beta]}$; (ii) the probability that the largest domain in $\alpha[\beta]$ has a state equal to $M_{\beta[\alpha]}$, designed by $P_{\beta[\alpha]}(M_{\alpha[\beta]})$; (iii) the probability ϕ of finding a localized coherent state in the system (either population coherent, the other disordered).

Figure 2 shows these quantities as functions of the parameter Q , for a fixed value $B = 0.05$. The qualitative behavior of the system is similar for other values of B and also for different sizes of the partitions of the two populations. The probability $P_{\alpha}(M_{\beta}) = 1$ for values $Q > Q_c = 0.004$, indicating that the state of the largest domain in α is always equal to that imposed by the field M_{β} . For values Q close to 1, each population reaches a homogeneous state with $S_{\alpha[\beta]} = 1$. This means that, for this range of Q , the global field M_{β} imposes its state on population α and, correspondingly, the field M_{α} imposes its state on population β . Consequently, both populations reach the same homogeneous state with $M_{\alpha} = M_{\beta}$. This asymptotic state is shown in Fig. 1(a). However, for very small values of B , the spontaneous coherence arising in population α for parameter values $Q > Q_c$ due to the agent-agent interactions competes with the order being imposed by the applied global field M_{β} . For some realizations of initial conditions, the homogenous state in population $\alpha[\beta]$ does not always coincides with the state of the applied global field $M_{\beta[\alpha]}$. In that case populations α and β may reach homogeneous states different from each other, where $M_{\beta} \neq M_{\alpha}$. This state is displayed in Fig. 1(b). For values $Q < Q_c, \forall B$, both populations reach disordered states, characterized by $S_{\alpha} \simeq S_{\beta} \simeq 0$. The corresponding pattern is exhibited in Fig. 1(d).

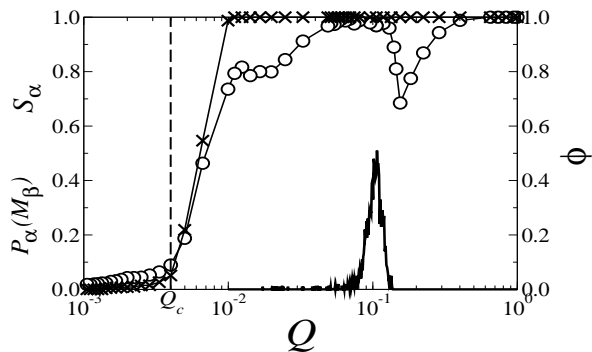


FIG. 2: S_{α} , $P_{\alpha}(M_{\beta})$, and the probability ϕ of finding a localized ordered state in the system, as functions of the parameter Q with $F = 10$, for fixed $B = 0.05$. Each data point is the result of averaging over 100 realizations of initial conditions. System size is $N = 800$ with partition $N_{\alpha} = 0.6N$. Left vertical axis: S_{α} (open circles); $P_{\alpha}(M_{\beta})$ (crosses). Right vertical axis: probability ϕ (continuous thick line). Disordered states occur for values $Q < Q_c = 0.004$.

Note that $S_{\alpha} < 1$ for some ranges of values of Q , indicating that for those values the largest domain in population α does not entirely occupy that population. This

corresponds to a state of partial coherence for both populations.

As shown in Fig. 1(c), localized coherent states are configurations where a homogeneous state can arise in only one population, while the other remains inhomogeneous. In contrast to the other homogeneous states that can be characterized by statistical quantities calculated in just one population, a localized coherent state is defined by considering both populations simultaneously, i.e., it requires the observation of the entire system. A localized coherent state is characterized by $S_{\alpha[\beta]} = 1$ and $S_{\beta[\alpha]} = u < 1$, where u is some threshold value. Figure 2 shows the probability ϕ of finding a localized coherent state in the system as a function of q , employing the criterion $u \leq 0.6$. There are ranges of the parameter Q where localized coherent states can emerge; the probability ϕ is maximum immediately before the value of Q corresponding to a local minimum of S_{α} . Note that the region of the parameter Q where localized coherent states appear in the system lie between a common homogeneous state and a partially coherent state. The configuration of localized coherent states shares features of both of these states.

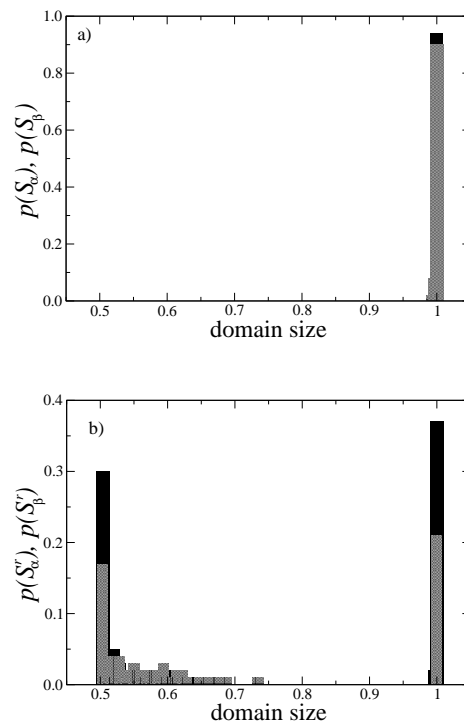


FIG. 3: Probability distributions $p(\alpha)$ and $p(\beta)$ of normalized domain sizes for populations α (black bars) and β (grey bars), calculated over 100 realizations of initial conditions, with fixed $B = 0.05$ and for different values of Q . (a) $Q = 0.65$ (common homogenous state); (b) $Q = 0.105$ (localized coherent states).

Figure 3 shows the probability distributions $p(\alpha)$ and $p(\beta)$ of the normalized domain sizes for populations α and β , respectively, calculated over 100 realizations of

initial conditions, for different values of Q , and with fixed $B = 0.05$ corresponding to Fig. 2. Figure 3(a) exhibits the probabilities $p(\alpha)$ and $p(\beta)$ with $Q = 0.65$, corresponding to a common homogeneous state characterized by the presence of one large domain in each population whose size is of the order of that population size $S_\alpha[S_\beta] \sim 1$. Figure 3(b) shows $p(\alpha)$ and $p(\beta)$ for $Q = 0.105$, corresponding to the emergence of localized coherent states in the system. In this case either population can reach a homogeneous configuration, $S_\alpha[S_\beta] \sim 1$, or an inhomogeneous state ($S_\alpha^1[S_\beta^1] < 0.6$). Once formed, a localized coherent state is stable. These states arise for different partitions of the two populations.

In summary, we have investigated the emergence of localized coherent behavior in a system consisting of two interacting populations of social agents. Our model contains two main ingredients: (i) the possibility of non-interacting states in the interaction dynamics, and (ii) the presence of reciprocal global interactions between the populations. The global interaction field associated to each population corresponds to the statistical mode of the states of the agents. In the context of social dynamics, this global field can be interpreted as mass media messages about “trends” originated in one population and being transmitted to the other population.

We have found localized coherent states, consisting of one population in a homogeneous state and the other in an disordered state. These configurations occur with a probability that depend on both parameters B and Q . They can be considered as intermediate configurations between a partially coherent state and a common homogeneous state. These localized coherent states are reminiscent of the chimera states that have been found in two populations of dynamical oscillators having global or long range interactions, where one population in a co-

herent state coexist with the other in a incoherent state [7, 10–12]. In addition, other asymptotic collective behaviors can appear in the system depending on parameter values: a common homogeneous state, where both populations share the same state; different homogeneous states, where both population reach homogenous states but different from each other; and a disordered state, where both populations reach inhomogeneous states.

The observation of localized coherent states in the context of social dynamics suggests that the emergence of chimeralike states should be a common feature in distributed dynamical systems where global interactions coexist with local interactions. This phenomenon should also be expected in other non-equilibrium systems possessing the characteristic of non-interacting states, such as social and biological systems whose dynamics usually possess a bound condition for interaction. It would also be of interest to search for localized coherent states in complex networks of social agents, such as communities, where the interaction between populations occurs through a few elements rather than global fields.

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